

# Equação de Convecção-Difusão-Reação

Achar

$$u = u(x, y, t) \text{ tq}$$

$$\frac{\partial u}{\partial t} - \nabla \cdot (k \nabla u) + \beta \cdot \nabla u + \sigma u = f \text{ em } \Omega \times (0, t_f)$$

$$u(x, y, 0) = u_0(x) \quad \text{e} \quad u = g \text{ em } \partial\Omega$$

$$\sigma \geq 0, \|k\| \neq 0, \nabla \cdot \beta = 0, f \in L^2(\Omega); u: \Omega \times (0, t_f) \rightarrow \mathbb{R}$$

Método de Galerkin

Achar  $u_h \in X_h \subset H_0^1(\Omega)$  tq

$$\left( \frac{\partial u_h}{\partial t}, v_h \right) + B(u_h, v_h) = (f, v_h) \quad \forall v_h \in X_h \in H_0^1(\Omega)$$

ou seja,

Achar  $u_h \in X_h$  tq

$$\int_{\Omega} \frac{\partial u_h}{\partial t} v_h \, d\Omega + \int_{\Omega} \nabla u_h \cdot k \nabla v_h \, d\Omega + \int_{\Omega} \beta \cdot \nabla u_h v_h \, d\Omega + \int_{\Omega} \sigma u_h v_h \, d\Omega =$$

$$\int_{\Omega} f v_h \, d\Omega \quad \forall v_h \in X_h$$

# Métodos Variacionais Estabilizados

Achar  $u_h \in X_h$  tq

$$\underbrace{\left( \frac{\partial u_h}{\partial t}, v_h \right) + B(u_h, v_h)}_{\text{Galerkin}} + \underbrace{E(u_h, v_h)}_{\text{Termo de Perturbação}} = (f, v_h) \quad \forall v_h \in X_h$$

onde,

$$E(u_h, v_h) = \sum_{\Omega_e \in T_h} \int_{\Omega_e} (\Delta u_h - f) \tau_h P(v_h) d\Omega$$

$P(\cdot)$  é um operador aplicado no espaço das funções testes - caracteriza cada método estabilizado

$\tau_h$  é um parâmetro de estabilização;

$(\Delta u_h - f) = R(u_h)$  é o resíduo da equação diferencial.

SUPG (Streamline Upwind Petrov-Galerkin):

$$P(u_h) = \beta \cdot \nabla v_h$$

$$\Delta u_h - f = R(u_h) = \frac{\partial u_h}{\partial t} - \nabla \cdot (k \nabla u_h) + \beta \cdot \nabla u_h + f u_h - f$$

ou seja,

Achar  $u_h \in X_h$  tq

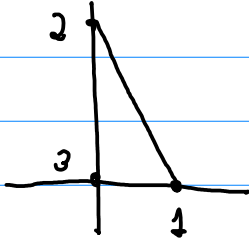
$$\int_{\Omega} \frac{\partial u_h}{\partial t} v_h d\Omega + \int_{\Omega} \nabla u_h \cdot k \nabla v_h d\Omega + \int_{\Omega} \beta \cdot \nabla u_h v_h d\Omega + \int_{\Omega} f u_h v_h d\Omega +$$

$$\sum_{\Omega_e \in T_h} \tau_h \int_{\Omega_e} \frac{\partial u_h}{\partial t} \beta \cdot \nabla v_h d\Omega - \sum_{\Omega_e \in T_h} \tau_h \int_{\Omega_e} \nabla \cdot (k \nabla u_h) \beta \cdot \nabla v_h d\Omega + \sum_{\Omega_e \in T_h} \tau_h \int_{\Omega_e} \beta \cdot \nabla u_h \beta \cdot \nabla v_h d\Omega$$

$$+ \sum_{\Omega_e \in T_h} \int_{\Omega_e} \tau_h \beta \cdot \nabla u_h \, d\Omega = \int_{\Omega} f u_h \, d\Omega + \sum_{\Omega_e \in T_h} \int_{\Omega_e} f u_h \beta \cdot \nabla u_h \, d\Omega$$

$\forall u_h \in X_h$

considerando Elemento triangular linear:



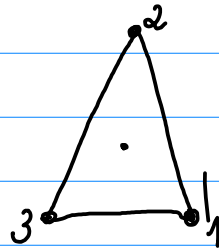
$$N_1(\xi, \eta) = \xi$$

$$N_2(\xi, \eta) = \eta$$

$$N_3(\xi, \eta) = 1 - \xi - \eta$$

$$[\nabla N_i] = B = \frac{1}{2A^e} \begin{bmatrix} y_{23} & y_{31} & y_{12} \\ x_{32} & x_{13} & x_{21} \end{bmatrix}$$

$$u_h^e = \sum_{k=1}^3 u_k N_k$$



$$N = [N_1 \quad N_2 \quad N_3]$$

$$u_h^e = N_i$$

$$\frac{\partial u_h^e}{\partial t} = \sum_{k=1}^3 \dot{u}_k N_k, \text{ onde } \dot{u}_k \text{ é o valor nodal de } \frac{\partial u_h^e}{\partial t}$$

$$f^e = \sum_{k=1}^3 f_k N_k$$

A formulação SUPG resulta em um sistema de equações diferenciais ordinárias dado por:

$$M \dot{U} + K U = F$$

onde nel

$$M = A \left( M_G^e + M_{PG}^e \right)$$

$$K = A \left( D_G^e + D_{PG}^e + A_G^e + A_{PG}^e + R_G^e + R_{PG}^e \right)$$

$$F = A \left( F_G^e + F_{PG}^e \right)$$

A seguir associamos cada parcela da formulação a sua respectiva matriz local.

$$M_G^e : \int_{\Omega_e} \frac{\partial u_h}{\partial t} u_h d\Omega$$

$$M_{PG}^e : \int_{\Omega_e} \tilde{u}_h \frac{\partial u_h}{\partial t} \beta \cdot \nabla u_h d\Omega$$

$$D_G^e : \int_{\Omega_e} \nabla u_h \cdot k \nabla u_h d\Omega$$

$$D_{PG}^e : - \int_{\Omega_e} (\tilde{u}_h \nabla \cdot (k \nabla u_h)) \beta \cdot \nabla u_h d\Omega$$

$$A_G^e : \int_{\Omega_e} \beta \cdot \nabla u_h u_h d\Omega$$

$$A_{PG}^e : \int_{\Omega_e} \tilde{u}_h \beta \cdot \nabla u_h \beta \cdot \nabla u_h d\Omega$$

$$R_G^e : \int_{\Omega_e} r u_h u_h d\Omega$$

$$R_{PG}^e : \int_{\Omega_e} \tilde{u}_h \nabla u_h \beta \cdot \nabla u_h d\Omega$$

$$F_G^e : \int_{\Omega_e} f u_h d\Omega$$

$$F_{PG}^e : \int_{\Omega_e} \tilde{u}_h f \beta \cdot \nabla u_h d\Omega$$

$$M_G^e = \int_{\Omega_e} N^T N d\Omega = \frac{A^e}{12} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

$$M_{PG}^e = \int_{\Omega_e} \tilde{u}_h B^T \beta N d\Omega = \tilde{u}_h B^T \beta \int_{\Omega_e} N d\Omega$$

$$M_{PG}^e = \frac{1}{2A^e} \begin{bmatrix} y_{23} & x_{32} \\ y_{31} & x_{13} \\ y_{12} & x_{21} \end{bmatrix} \begin{bmatrix} \beta_x \\ \beta_y \end{bmatrix} \frac{2A^e}{6} \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} m_1 & m_1 & m_1 \\ m_2 & m_2 & m_2 \\ m_3 & m_3 & m_3 \end{bmatrix}, \quad \text{onde } \begin{aligned} m_1 &= y_{23}\beta_x + x_{32}\beta_y \\ m_2 &= y_{31}\beta_x + x_{13}\beta_y \\ m_3 &= y_{12}\beta_x + x_{21}\beta_y \end{aligned}$$

$$D_G^e = \int_{\Omega_e} B^T k B \, d\Omega$$

$$= \frac{1}{2A^e} \begin{bmatrix} y_{23} & x_{32} \\ y_{31} & x_{13} \\ y_{12} & x_{21} \end{bmatrix} \begin{bmatrix} k_{xx} & k_{xy} \\ k_{yx} & k_{yy} \end{bmatrix} \frac{1}{2A^e} \begin{bmatrix} y_{23} & y_{31} & y_{12} \\ x_{32} & x_{13} & x_{21} \end{bmatrix} A^e$$

$$= \frac{1}{4A^e} \begin{bmatrix} -(d_{12}+d_{13}) & d_{12} & d_{13} \\ d_{12} & -(d_{12}+d_{23}) & d_{23} \\ d_{13} & d_{23} & -(d_{13}+d_{23}) \end{bmatrix} \begin{aligned} d_{12} &= y_{31}(k_{xx}y_{23} + k_{yx}x_{32}) + x_{13}(k_{xy}y_{23} + k_{yy}x_{32}) \\ d_{13} &= y_{12}(k_{xx}y_{23} + k_{yx}x_{32}) + x_{21}(k_{xy}y_{31} + k_{yy}x_{13}) \\ d_{23} &= y_{12}(k_{xx}y_{31} + k_{yx}x_{13}) + x_{21}(k_{xy}y_{31} + k_{yy}x_{13}) \end{aligned}$$

$D_{PG}^e = 0$ , pois  $\nabla \cdot (k \nabla u_n) = 0$  para aproximação linear!

$$A_G^e = \int_{\Omega_e} N^T \beta^T B \, d\Omega = \int_{\Omega_e} N^T \, d\Omega \, \beta^T B$$

$$= \frac{2A^e}{6} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} \beta_x & \beta_y \end{bmatrix} \frac{1}{2A^e} \begin{bmatrix} y_{23} & y_{31} & y_{12} \\ x_{32} & x_{13} & x_{21} \end{bmatrix} = \frac{1}{6} \begin{bmatrix} a_1 & a_2 & a_3 \\ a_1 & a_2 & a_3 \\ a_1 & a_2 & a_3 \end{bmatrix}$$

onde,

$$\begin{aligned} a_1 &= \beta_x y_{23} + \beta_y x_{32} = m_1 \\ a_2 &= \beta_x y_{31} + \beta_y x_{13} = m_2 \\ a_3 &= \beta_x y_{12} + \beta_y x_{21} = m_3 \end{aligned}$$

A menos das constantes  $A_G^e = (M_{PG}^e)^T$

$$\begin{aligned}
 A_{FG}^e &= \tau_h \int_{\Omega} B^T \beta \beta^T B \, d\Omega \\
 &= \tau_h \frac{1}{2A^e} \begin{bmatrix} y_{23} & x_{32} \\ y_{31} & x_{13} \\ y_{12} & x_{21} \end{bmatrix} \begin{bmatrix} \beta_x \beta_x & \beta_x \beta_y \\ \beta_y \beta_x & \beta_y \beta_y \end{bmatrix} \frac{1}{2A^e} \begin{bmatrix} y_{23} & y_{31} & y_{12} \\ x_{32} & x_{13} & x_{21} \end{bmatrix} A^e \\
 &= \frac{\tau_h}{4A^e} \begin{bmatrix} -(a_{12} + a_{13}) & a_{12} & a_{13} \\ -(a_{12} + a_{23}) & a_{23} & \\ -(a_{13} + a_{23}) & & \end{bmatrix} \begin{matrix} a_{12} = y_{31}(\beta_x x_{23} + \beta_y x_{32}) + x_{13}(\beta_x y_{23} + \beta_y y_{32}) \\ a_{13} = y_{12}(\beta_x y_{23} + \beta_y x_{32}) + x_{21}(\beta_x y_{31} + \beta_y y_{13}) \\ a_{23} = y_{12}(\beta_x y_{31} + \beta_y x_{23}) + x_{21}(\beta_x y_{13} + \beta_y y_{31}) \end{matrix}
 \end{aligned}$$

$$\begin{aligned}
 R_G^e &= \int_{\Omega^e} \sigma N^T N \, d\Omega \\
 &= \frac{\sigma A^e}{12} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}
 \end{aligned}$$

$$R_{FG}^e = \int_{\Omega^e} \sigma \tau_h N^T \beta^T B \, d\Omega = \frac{\sigma \tau_h}{6} \begin{bmatrix} a_1 & a_2 & a_3 \\ a_1 & a_2 & a_3 \\ a_1 & a_2 & a_3 \end{bmatrix}$$

$$F_G^e = \int_{\Omega^e} N^T \sum_{i=1}^3 f_i N_i \, d\Omega = \frac{A^e}{12} \begin{bmatrix} 2f_1 + f_2 + f_3 \\ f_1 + 2f_2 + f_3 \\ f_1 + f_2 + 2f_3 \end{bmatrix}$$

$$\begin{aligned}
 F_{FG}^e &= \int_{\Omega^e} \tau_h \sum_{i=1}^3 f_i N_i B^T \beta \, d\Omega = \frac{\tau_h}{2A^e} \begin{bmatrix} y_{23} & x_{32} \\ y_{31} & x_{13} \\ y_{12} & x_{21} \end{bmatrix} \begin{bmatrix} \beta_x \\ \beta_y \end{bmatrix} \frac{2A^e}{6} (f_1 + f_2 + f_3) \\
 &= \frac{\tau_h}{6} (f_1 + f_2 + f_3) \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}
 \end{aligned}$$